# Time Synchronization For An Optically Groomed Data Center Network

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#### Time Synchronization Mechanisms for an Optically Groomed Data Center Network

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# Agenda

- Objective
- Highlights of the Architecture
- Features of the Communication Scheme
- Time Synchronization Schemes
  - Continuous Time Approach
  - Discrete-time based approach
- Observation
- Performance Evaluation
- Comparison of Time Synchronization Schemes





# Objective

- > Optically groomed data center network(OGDCN)
- ➢Power efficient hybrid optical-packet switched network.
- ≻Time synchronization aspect of transmission scheduling in OGDCN.
- Two schemes Continuous and Discrete time(slotted) based time synchronization.
- ≻Performance evaluation and comparison.

G. C. Sankaran and K. M. Sivalingam, "Optical traffic grooming based data center networks: Node architecture and comparison," *IEEE Journal on Selected Areas in Communications – Series on Green Communica- tions and Networking*, vol. 34, pp. 1618–1630, May 2016.



Interconnected core.

Fig. 1: Three-tier Data Center Network (DCN) topology.

- > Each core connected to N aggregate switch.
- > Each aggregate switch connected to M TOR switches.
- > Each TOR connected to p compute and storage nodes(CSN).
- > CSNs are equipped with tunable transceivers only.

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# **Features of the Communication Scheme**

- Source-destination pair must tune to a predefined wavelength.
- A centralized controller computes the transmission schedule.
- To compute a schedule, all network resources must be available for transmission duration(no network path establishment required).
- This includes transmitter, receiver and the specific wavelength on all link segments along the path.
- Controller uses separate control wavelength to carry control messages(packet switched).
- CSN nodes communicates with each other using WDM and TDM.



#### **Features of the Communication Scheme**



Fig. 1: Three-tier Data Center Network (DCN) topology.



Fig. 2: Shared wavelength circuits for CSNs connected to ToR  $T_{11}$ .



### **Time Synchronization Schemes**

#### **Continuous Time based approach :**

A high precision clock is used to interpret transmission start and finish times consistently.  $\mathcal{D}_{b}$   $\mathcal{D}_{f}$ 

- Considering propagation delay, Db > Pb > Sb
- $Pb Sb = \alpha ui + \beta ij$   $Db Pb = \gamma jv$   $Db Sb = \delta uv$   $\delta uv = \alpha ui + \beta ij + \gamma jv$



Fig. 4: Impact of propagation delay on resource reservation across the network. Here,  $\delta_{uv} = \alpha_{ui} + \beta_{ij} + \gamma_{jv}$ .

# **Continuous Time Approach**

- Propagation delays are continuous values, so accurate clocks are required
- Network time protocol/precision time protocol is used

Link Utilization :

 $U_c = 1 - \frac{W}{\overline{L} + W}$  Maximum wastage ratio

W= rounding-off error in bits. e.g. for 10 Gbps data rate 1 nanosecond accuracy, W= 10 bits.

*L* = average packet length.

Example: W=10 bits, packet length range 64-8192 bytes(avg.= 4128 bytes), Maximum utilization is 99.9% UCDAVIS

## **Discrete Time Approach**

*Time is divided into slots of constant duration(S). Slot start times must be consistently interpreted across the network.* 

- Propagation delay=  $\delta^*$  (constant)
- Actual propagation delay= $\delta_{uv}$
- Time slot duration = S
- Effective time slot duration = S'
- $r_0, r_1$  = receiver start time to receive for slot 0,1
- $t_0 t_1$  = transmitter start time to transmit slot 0,1



Fig. 5: Effective duration S' less than actual time slot duration S with Discrete time (DT) choice.

#### **Discrete Time Approach**

**Case 1**:  $\delta^* < \delta_{uv}$ 

avoid overlap, the effective transmission duration within the slot

 $(r0 + \delta_{21} - \delta^*, r_1)$ ; S'<S

 $\delta^* > \delta_{uv}$  negative time offset

 $(r_0, r_1 + \delta_{20} - \delta^*)$ ; S'>S

**Case 2:Ideal case** 

 $(r_{0}, r_{1})$ 



Fig. 5: Effective duration S' less than actual time slot duration S with Discrete time (DT) choice.



# **Discrete Time Approach**

**Delay Compensation** : A constant propagation delay is considered. **No Delay Compensation** : No constant propagation delay is considered.

**Link Utilization :** 
$$U_d = \frac{L}{S} \left[ 1 - \frac{\sigma}{S} \right]$$

L = average data transfer length

- $\sigma$  = standard deviation of the propagation delay
- S = size of the time slot

Example: slot length= 8192 bytes, avg. data length= 4128 byte,  $\sigma$ =0 (delay compensation case). Utilization cannot exceed 50%, for data transfer length = slot length, this network can be fully utilized.<sup>UCDAVIS</sup>

#### **Observations**

Continuous time scheme investigated in DCN

Utilization of CT synchronization depends on per transfer wastage W.

W depends on the accuracy of the clock being used.

Utilization of DT synchronization depends on propagation delay deviation, average transfer length.



### **Performance Evaluation**

- Scheduling algorithm : Earliest first & Bitmap heuristic.
- *Throughput = number of shared wavelength circuits x number of wavelength x data rate*
- Utilization = Busy Duration / Total duration
- CH= continuous time synchronization with high accuracy (1ns)
- CL= continuous time synchronization with low accuracy (1000ns)



#### **Performance of CT Synchronization**



Fig. 6: Throughput and delay of continuous-time (CT) scheme with varying time accuracy.

#### **Observations :**

- 1. Variation of delay and throughput with the offered traffic load.
- 2. Higher accuracy increases throughput.
- 3. No significant difference for 1 ns & 100 ns accuracy.
- 4. Throughput difference was less than 0.1 % and their delay difference varied from 56 ns (3.526 and 3.582  $\mu$ s) to 9  $\mu$ s (254 and 263  $\mu$ s). This is not significant considering the delay of a DCN.



#### **Performance of DT Synchronization**



#### **Observation :**

- 1. Delay compensation is able to accommodate more packets & higher throughput at all load.
- 2. Delay compensation improves performance of DT scheme.

# **Performance of DT Synchronization**

#### Varying packet lengths:

(i)**DTC:** packets of constant length of 8192 bytes.

(ii)**DTT:** packets following a tri-modal distribution with modes at 64, 1500 and 8192 bytes.

(iii)**DTU:** uniform packet length distribution, with packet lengths ranging from 64 to 8192 bytes.





### **Performance of DT Synchronization**



Fig. 8: Throughput and delay for Discrete time with fixed packet length (DTC), with trimodal distribution (DTT) and 5. with uniform distribution (DTU).

#### **Observations :**

- 1. Variation of delay and throughput with the varying packet length.
- DTC uses constant packet length of 8192 bytes and the throughput saturates at 36 Tbps.
- 3. DTT uses 5634 bytes of avg. packet length and throughput saturates at 24.76 Tbps.
- 4. DTU uses 4128 bytes of avg. packet length and throughput saturates at 18.14 Tbps.
  - . Packet delays are independent of the packet lengths.

## **Comparison of Time Synchronization Schemes**



Fig. 9: Throughput and delay for continuous time (CH) and discrete time with fixed packet length (DTC) varying network load.

#### **Observations :**

- 1. Packet delay increases steeply when load is higher than 80%
- 2. Throughput of DTC achieve 37 Tbps.
- 3. CH limits at full load as the controller bandwidth(800 Gbps) saturates.
- 4. Delay obtained by CH is 80 us, DTC is 140 us.
- 5. CT performs better without any packet length restriction.



# Conclusion

- Optically groomed DCNs offer optically transparent end to end path between any source and destination, the network can readily support higher data rates and hence throughput.
- DT synchronization is affected by propagation delay variance and packet length distribution.
- CT synchronization requires reasonably good accuracy (100 ns) to avoid any significant performance impact.

CT synchronization appears to be promising for OGDCN specifically and to all DCNs in general.



# Thanks!



