Constraint Programming (CP) and IBM CP Optimizer

Speaker: Xinbo Wang



Outline

- A glimpse of Constraint Programming (CP)
- A glimpse of Integer Mathematical Programming (MP)
 - Comparison of CP and MP
- $\cdot~$ A brief introduction of IBM CP optimizer



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What is constraint programming?

- CP is an optimization technology which is complementary to Mathematical programming (e.g. ILP) taking a different approach to optimization, but sharing similarities.
- It is a relatively new technology developed in the computer science and artificial intelligence communities.
- It has found an important role in scheduling and highly combinational problems (for ours).



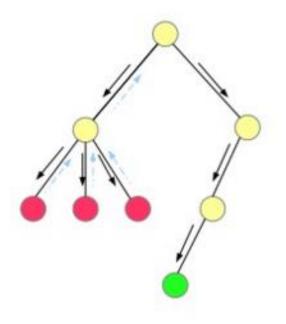
Applications

- Job shop scheduling
- Assembly line smoothing and balancing
- Cellular frequency assignment
- Airline crew rostering Nurse scheduling
- Shift planning
- Maintenance planning
- and scheduling
- Airport gate allocation and stand planning
- Production scheduling
- Transport scheduling
- Warehouse management
- Course timetabling



How Constraint Programming Works?

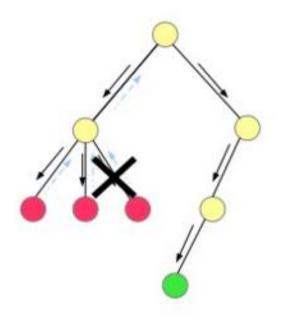
- CP is a constructive approach
- Values are assigned to variables one at a time to extend a partial solution to a complete solution
- At a point, it may be useless to further extend a partial solution as at least one constraint is already violated by the partial solution
 - The solver backtracks and tries a different value for a previously assigned variable
 - All possible assignments of values to variables can be examined in this way





How Constraint Programming Works?

- In CP, the basic search behaviour is tree search
- Including search space reduction via domain filtering
- Domain filtering
 - Before each value-variable assignment, *domain filtering* occurs
 - Each value of a variable which cannot be used in a solution (given the current partial assignment) can be removed
 - Each constraint type has a specialized algorithm which filters domains





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What is Integer Linear Programming?

 An integer programming problem is a mathematical optimization or feasibility program in which some or all of the variables are restricted to be integers.

 x_i

- The objective function and the constraints (other than the integer constraints) are linear.
- Mixed integer linear programming (MILP) involves problems in which only some of the variables are constrained to be integers, while other variables are allowed to be non-integers.
- Zero-one linear programming involves problems in which the variables are restricted to be either 0 or 1. Note that any bounded integer variable can be expressed as a combination of binary variables. For example, given an integer variable, x, the variable can be expressed :

$$x = x_1 + 2x_2 + 4x_3 + \ldots + 2^{\lfloor \log_2 U \rfloor} x_{\lfloor \log_2 U \rfloor + 1}.$$



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Comparison

- CP works with the same concepts as mathematical programming: decision variables, objective function, and constraints.
- CP only discrete decision variables (integer or Boolean) vs
 MP discrete and continuous decision variables.
- CP logical constraints and arithmetic expressions (modulo, integer division, etc.) vs MP models only linear constraints or quadratic convex constraints.
 - CP no limitation on the arithmetic constraints that can be set on decision variables vs MP specific to a class of problems whose solution space satisfies certain mathematical properties.
 - Each optimization engine uses different techniques and algorithms to find feasible solutions and optimize them.



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A Tabular View

Constraint programming vs. mathematical programming

Feature	MP	СР
Relaxation	Yes	No
GAP measure	Yes	No
Optimality proof	Yes	Yes
Modeling limitations	Quadratic problems are limited to PSD (Positive Semi Definite) problems and Second Order Cone Programming (SOCP) problems	Discrete problems
Specialized constraints	No	Yes
Logical constraints	Yes	Yes
Theoretical grounds	Algebra	Graph theory and algorithmic
Modeler support	Yes	Yes
Model and run	Yes	Yes



Benefits of constraint programming

- Solve time tabling problems and sequencing problems.
- An alternative to mathematical programming for allocation problems that have a slow convergence.
 - Constraint programming has native support for:
 - ✓ Nonlinear costs or constraints
 - ✓ Logical constraints and statements
 - ✓ Constraints on and between interval variables
 - Compatibility or incompatibility constraints
 - ✓ More useful features



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Arithmetic constraints

- ✓ x + y, x − y, x * y, x / y, x div y, x % y
- ✓ min, max, abs, log, exp etc.
- ✓ Piecewise linear functions
- **Relational constraints**

✓ x == y, x != y, x <= y, x < y, lb <= x <= ub</p>

- Logical constraints
 - ✓ !c, c||d, c && d,
 - \checkmark c => d , c => d else e
 - ✓ c and d are relational or conditional constraints



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· Reification

 Relational or logical constraints can be used in a value context, where they evaluate to 0 or 1

Examples

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- ✓ Arithmetic: max(0, abs(load[i] cap))
- ✓ Relational: wid * hei * depth * density <= maxLoad</p>
- ✓ Logical: end[i] <= start[j] || start[j] <= end[i]</pre>
- ✓ Reification: spill == (load[i] > cap)



Count expression

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- ✓ count(dvar int[] x, int c)
- \checkmark Evaluates the number of variables in x with value c
- \checkmark e.g. Count the number of nurses allocated to ward 5
 - count(wardAllocation, 5) >= 3

Element expression

- \checkmark (int[] a)[dvar int x] OR (dvar int[] a)[dvar int x]
- \checkmark Evaluates to the xth member of a
- e.g. travel == 2 * distFromPittsburgh[holidayTown]
- ✓ travel and holidayTown are variables



· All Different

- ✓ allDifferent(dvar int[] x)
- ✓ All variables in x must take different values
- \checkmark e.g. The rank (visit priority) of each city is different
 - allDifferent(rankOfVisit)

Allowed / Forbidden assignments

- allowedAssignments({<a,b,c>} A, dvar int[3] x)
- \checkmark The assignments to x must fit with a tuple of A
- ✓ forbiddenAssignments is the negation of this



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Expressions and Constraints

Bin packing constraint

- ✓ pack(dvar int[m] ld, dvar int[n]x, int[n] sz, dvar int c)
- ✓ Id[i] == sum(j) (x[j] == i) * sz[j]
 - c is the number of containers used

Inverse constraint

- inverse(dvar int[n] x, dvar int[n] y)
- \checkmark x[i] == j <=> y[j] == i --- link primary and dual models
- Lexicographic ordering constraint
 - ✓ lex(dvar int[n] x, dvar int[n] y) --- break symmetries



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What is CP Optimizer

- A Constraint Programming engine with an emphasis on modelling and automatic search
- Available as a toolkit in C++ , Java, .NET
 - C++ is the native language and allows more possibilities, like writing incremental custom constraints, and fully controlling the search process
- Available as an engine inside ILOG OPL IDE
 - ✓ ILOG: name of the company (acquired by IBM)
 - ✓ OPL: optimization programming language
 - ✓ Higher level modelling and data manipulation



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Overview of an CP Model using OPL

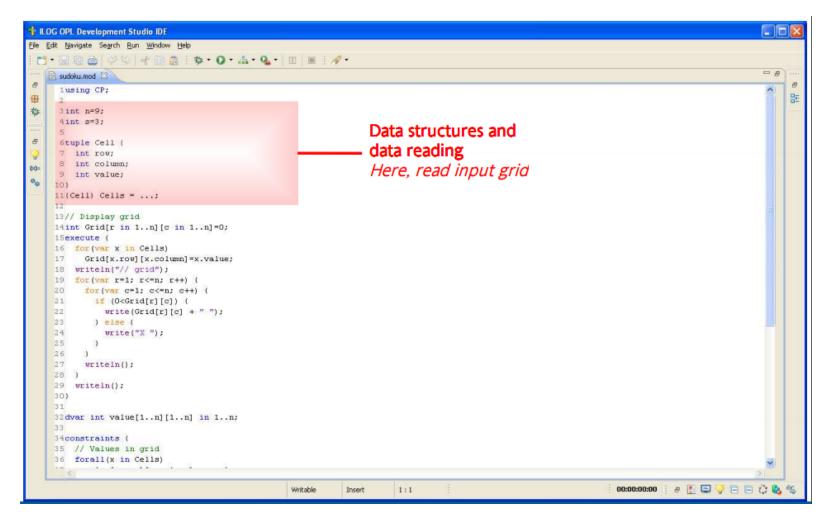
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- ✓ Data manipulation and pre-processing
 - declarative (expressions) and/or imperative (script)
- ✓ Variable declarations
- · Middle
 - ✓ Declarative model
 - objective (optional) and constraints
- Bottom
 - ✓ Post-processing of solutions
 - ✓ Declarative (expressions) and/or imperative (script)



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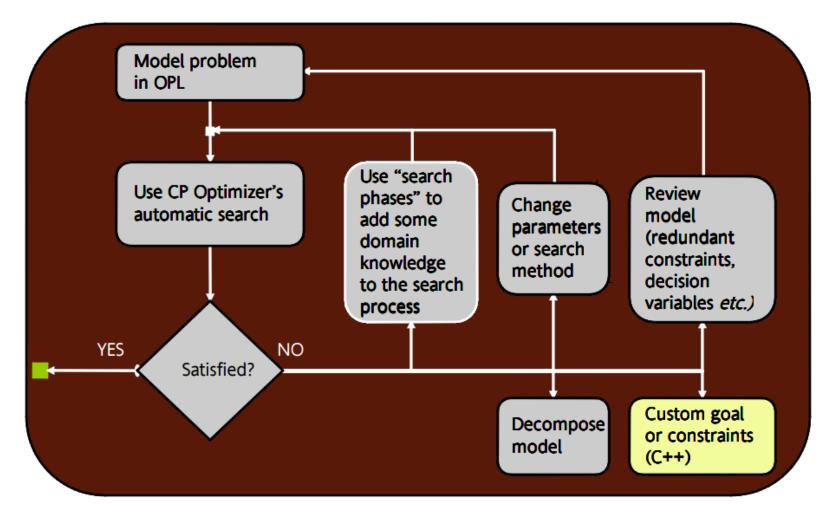


Search in CP Optimizer

- Automatic search is emphasized
 - Simpler, more maintainable, benefit from upgrades
- Search Phases
 - ✓ What group of variables to assign first
 - ✓ (optionally) define instantiation strategy
- · Parameters
 - ✓ Inference levels and search control parameters
- Problem still hard?
 - ✓ Improve model
 - ✓ Simplify or relax specification

✓ Decompose: CPLEX often useful here Slide 30

Typical Use of CP Optimizer







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